

矩形截面异质柱体在半无限弹性体内的 热应力问题*

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一、含有矩形截面异质柱的无限弹性体的热应力问题

如图1所示,无限弹性体内装有矩形截面异质柱,柱轴平行于 z 轴,设 $c > 0$,异质柱的热胀系数 α_i 大于无限弹性体的热胀系数 α_a ,但两种材料有相同的弹性系数。当温度等于零时,这个组合体里无应力存在;当组合体的温度 T_0 大于零时,试求解这个组合体的热应力问题。

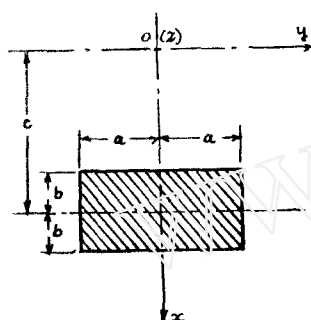


图1 含有矩形截面异质体的无限弹性体

按热弹性理论,这里的有关微分方程是

$$\nabla^2 \Phi = \frac{1+\nu}{1-\nu} \alpha T = \begin{cases} K, & \text{当 } c-b \leq x \leq c+b, -a < y < a \text{ 时,} \\ 0, & \text{当 } x < c-b, x > c+b, y < -a, y > a \text{ 时,} \end{cases} \quad (1)$$

其中 $K = \frac{1+\nu}{1-\nu} \eta_0 T_0$, $\eta_0 = \alpha_i - \alpha_a$, ν 是 Poisson 比, $\nabla^2 = \partial^2/\partial x^2 + \partial^2/\partial y^2$ 。

按照场论,公式(1)的解答是热弹性位移势函数 Φ :

$$\Phi = \frac{K}{2\pi} \int_{\xi=c-b}^{c+b} \int_{\eta=-a}^a \ln r d\xi d\eta, \quad r = \sqrt{(x-\xi)^2 + (y-\eta)^2}. \quad (2)$$

以 G 代表剪切模量,相应于 Φ 的应力和位移是:

$$\begin{aligned} \bar{\sigma}_x &= -2G \frac{\partial^2 \Phi}{\partial y^2} = -\frac{GK}{\pi} \iint_A \frac{(x-\xi)^2 - (y-\eta)^2}{[(x-\xi)^2 + (y-\eta)^2]^2} d\xi d\eta \\ &= -\frac{GK}{\pi} \int_{x-c+b}^{x-c-b} \left[\frac{y-a}{\xi^2 + (y-a)^2} - \frac{y+a}{\xi^2 + (y+a)^2} \right] d\xi \\ &= -\frac{GK}{\pi} \left[\arctg \frac{x-c-b}{y-a} - \arctg \frac{x-c+b}{y-a} - \arctg \frac{x-c-b}{y+a} + \arctg \frac{x-c+b}{y+a} \right], \\ \bar{\sigma}_y &= -2G \frac{\partial^2 \Phi}{\partial x^2} = -\frac{GK}{\pi} \iint_A \frac{(y-\eta)^2 - (x-\xi)^2}{[(x-\xi)^2 + (y-\eta)^2]^2} d\xi d\eta \end{aligned} \quad (3)$$

* 1964年7月13日收到。

$$= -\frac{GK}{\pi} \left[\arctg \frac{y-a}{x-c-b} - \arctg \frac{y+a}{x-c-b} - \arctg \frac{y-a}{x-c+b} + \arctg \frac{y+a}{x-c+b} \right], \quad (4)$$

$$\begin{aligned} \bar{\tau}_{xy} &= 2G \frac{\partial^2 \Phi}{\partial x \partial y} = -\frac{2GK}{\pi} \iint_A \frac{(x-\xi)(y-\eta)}{[(x-\xi)^2 + (y-\eta)^2]^2} d\xi d\eta \\ &= -\frac{GK}{\pi} \int_{c-b}^{c+b} \left[\frac{x-\xi}{(x-\xi)^2 + (y-a)^2} - \frac{x-\xi}{(x-\xi)^2 + (y+a)^2} \right] d\xi \\ &= \frac{GK}{2\pi} \ln \frac{[(x-c-b)^2 + (y-a)^2][(x-c+b)^2 + (y+a)^2]}{[(x-c-b)^2 + (y+a)^2][(x-c+b)^2 + (y-a)^2]}, \end{aligned} \quad (5)$$

利用关系 $\varphi \geq 0$ 时 $\arctg \varphi + \arctg \frac{1}{\varphi} = \pm \frac{\pi}{2}$, 就可验证

$$\bar{\sigma}_z = -2G\nabla^2 \Phi = \begin{cases} 2GK, & \text{在矩形截面之内;} \\ 0, & \text{在矩形截面之外;} \end{cases} \quad (6)$$

$$\begin{aligned} \bar{v} &= \frac{\partial \Phi}{\partial y} = \frac{K}{2\pi} \iint_A \frac{y-\eta}{(x-\xi)^2 + (y-\eta)^2} d\xi d\eta = \frac{K}{4\pi} \int_{x-c-b}^{x-c+b} \ln \frac{\xi^2 + (y-a)^2}{\xi^2 + (y+a)^2} d\xi = \\ &= \frac{K}{4\pi} \left\{ (x-c-b) \ln \frac{(x-c-b)^2 + (y-a)^2}{(x-c-b)^2 + (y+a)^2} - \right. \\ &\quad \left. - (x-c+b) \ln \frac{(x-c+b)^2 + (y-a)^2}{(x-c+b)^2 + (y+a)^2} + \right. \\ &\quad \left. + 2(y-a) \left[\arctg \frac{x-c-b}{y-a} - \arctg \frac{x-c+b}{y-a} \right] - \right. \\ &\quad \left. - 2(y+a) \left[\arctg \frac{x-c-b}{y+a} - \arctg \frac{x-c+b}{y+a} \right] \right\}, \end{aligned} \quad (7)$$

$$\begin{aligned} \bar{u} &= \frac{\partial \Phi}{\partial x} = \frac{K}{2\pi} \iint_A \frac{x-\xi}{(x-\xi)^2 + (y-\eta)^2} d\xi d\eta = \frac{K}{4\pi} \int_{y+a}^{y-a} \ln \frac{(x-c-b)^2 + \bar{\eta}^2}{(x-c+b)^2 + \bar{\eta}^2} d\bar{\eta} = \\ &= \frac{K}{4\pi} \left\{ (y-a) \ln \frac{(x-c-b)^2 + (y-a)^2}{(x-c+b)^2 + (y-a)^2} - \right. \\ &\quad \left. - (y+a) \ln \frac{(x-c-b)^2 + (y+a)^2}{(x-c+b)^2 + (y+a)^2} + \right. \\ &\quad \left. + 2(x-c-b) \left[\arctg \frac{y-a}{x-c-b} - \arctg \frac{y+a}{x-c-b} \right] - \right. \\ &\quad \left. - 2(x-c+b) \left[\arctg \frac{y-a}{x-c+b} - \arctg \frac{y+a}{x-c+b} \right] \right\}, \end{aligned} \quad (8)$$

其中双积分号下的 A 代表矩形截面的面积, 公式(3)至(8)即本节问题的解. 当然, 若仅求解本节的问题, 应使 $c=0$ 以求简化运算.

二、半无限弹性组合体的弹性力学边界值问题

现在考虑矩形截面异质体和半无限弹性体所组成的组合体 $x \geq 0$, $-\infty < z < \infty$ 和 $c > b$ 的热应力问题. 由于

$$(\bar{\sigma}_x)_{x=0} = \frac{GK}{\pi} \left[\arctg \frac{c+b}{y-a} - \arctg \frac{c-b}{y-a} - \arctg \frac{c+b}{y+a} + \arctg \frac{c-b}{y+a} \right] \neq 0$$

和

$$(\bar{\tau}_{xy})_{x=0} = \frac{GK}{2\pi} \ln \frac{[(c+b)^2 + (y-a)^2][(c-b)^2 + (y+a)^2]}{[(c+b)^2 + (y+a)^2][(c-b)^2 + (y-a)^2]} \neq 0,$$

所以须再解决保证半无限弹性组合体须具有自由表面的弹性力学边界值问题。为此, 先利用分部积分法由

$$\begin{aligned} \bar{\sigma}_0 = - \int_{-\infty}^{\infty} (\bar{\sigma}_x)_{x=0} e^{i\xi y} dy = - \frac{2GK}{\pi} \int_0^{\infty} & \left[\arctg \frac{c+b}{y-a} - \right. \\ & \left. - \arctg \frac{c-b}{y-a} - \arctg \frac{c+b}{y+a} + \arctg \frac{c-b}{y+a} \right] \cos(\xi y) dy \end{aligned}$$

导得

$$\begin{aligned} \bar{\sigma}_0 = - \frac{2GK}{\pi} \int_0^{\infty} \frac{\sin(\xi y)}{\xi} & \left[\frac{c+b}{(c+b)^2 + (y-a)^2} - \frac{c-b}{(c-b)^2 + (y-a)^2} - \right. \\ & \left. - \frac{c+b}{(c+b)^2 + (y+a)^2} + \frac{c-b}{(c-b)^2 + (y+a)^2} \right] dy, \end{aligned}$$

再利用变换 $y-a=y_1$ 和 $y+a=y_2$, 把上式化成

$$\begin{aligned} \bar{\sigma}_0 = - \frac{2GK}{\pi\xi} & \left(\int_{-a}^0 + \int_0^{\infty} \right) (\cos(\xi a) \sin(\xi y_1) + \sin(\xi a) \cos(\xi y_1)) \times \\ & \times \left[\frac{c+b}{(c+b)^2 + y_1^2} - \frac{c-b}{(c-b)^2 + y_1^2} \right] dy_1 + \\ & + \frac{2GK}{\pi\xi} \left(\int_{+a}^0 + \int_0^{\infty} \right) (\cos(\xi a) \sin(\xi y_2) - \sin(\xi a) \cos(\xi y_2)) \times \\ & \times \left[\frac{c+b}{(c+b)^2 + y_2^2} - \frac{c-b}{(c-b)^2 + y_2^2} \right] dy_2 = \\ = - \frac{2GK}{\pi} \frac{\sin(\xi a)}{\xi} & \int_0^{\infty} \left\{ (c+b) \left[\frac{\cos(\xi y_1)}{(c+b)^2 + y_1^2} dy_1 + \frac{\cos(\xi y_2)}{(c+b)^2 + y_2^2} dy_2 \right] - \right. \\ & \left. - (c-b) \left[\frac{\cos(\xi y_1)}{(c-b)^2 + y_1^2} dy_1 + \frac{\cos(\xi y_2)}{(c-b)^2 + y_2^2} dy_2 \right] \right\}, \end{aligned}$$

最后利用 $\int_0^{\infty} \frac{\cos(\alpha x)}{\alpha^2 + k^2} d\alpha = \frac{\pi}{2k} e^{-kx}$, 其中 $k > 0$, 即得

$$\bar{\sigma}_0 = - 2GK \frac{\sin(\xi a)}{\xi} (e^{-(c+b)|\xi|} - e^{-(c-b)|\xi|}). \quad (9)$$

另一方面, 可利用变换 $y-a=y_1$ 和 $y+a=y_2$ 把

$$\begin{aligned} \bar{\tau}_0 = - \int_{-\infty}^{\infty} (\bar{\tau}_{xy})_{x=0} e^{i\xi y} dy = \\ = - \frac{GKi}{\pi} \int_0^{\infty} \ln \frac{[(c+b)^2 + (y-a)^2][(c-b)^2 + (y+a)^2]}{[(c+b)^2 + (y+a)^2][(c-b)^2 + (y-a)^2]} \sin(\xi y) dy \end{aligned}$$

化为

$$\bar{\tau}_0 = - \frac{GKi}{\pi} \left\{ \left(\int_{-a}^0 + \int_0^{\infty} \right) [\cos(\xi a) \sin(\xi y_1) + \sin(\xi a) \cos(\xi y_1)] \times \right.$$

$$\begin{aligned}
& \times \ln \frac{(c+b)^2 + y_1^2}{(c-b)^2 + y_1^2} dy_1 + \\
& + \left(\int_{+a}^0 + \int_0^\infty \right) [\cos(\xi a) \sin(\xi y_2) - \sin(\xi a) \cos(\xi y_2)] \times \\
& \times \ln \frac{(c-b)^2 + y_2^2}{(c+b)^2 + y_2^2} dy_2 \Big\} = \\
& = \frac{2GKi}{\pi} \sin(\xi a) \int_0^\infty \ln \frac{(c-b)^2 + y_3^2}{(c+b)^2 + y_3^2} \cos(\xi y_3) dy_3;
\end{aligned}$$

又因

$$\pi \frac{e^{-\beta y} - e^{-\alpha y}}{y} = \int_0^\infty \ln \frac{\alpha^2 + x^2}{\beta^2 + x^2} \cos(xy) dx, \quad y > 0, \operatorname{Re} \alpha > 0, \operatorname{Re} \beta > 0,$$

所以得

$$\bar{v}_0 = 2GKi \frac{\sin(\xi a)}{|\xi|} (e^{-(c+b)|\xi|} - e^{-(c-b)|\xi|}). \quad (10)$$

现在若把公式(9)和(10)代入参考 Fourier 变换^[1]而导出的下列诸式:

$$\left. \begin{aligned}
\bar{\sigma}_x &= \frac{1}{2\pi} \int_{-\infty}^\infty e^{-|\xi|x-i\xi y} \{ [1 + |\xi|x] \bar{\sigma}_0 + ix\xi \bar{v}_0 \} d\xi, \\
\bar{\sigma}_y &= \frac{1}{2\pi} \int_{-\infty}^\infty e^{-|\xi|x-i\xi y} \left\{ [1 - |\xi|x] \bar{\sigma}_0 + i \frac{2|\xi| - \xi^2 x}{\xi} \bar{v}_0 \right\} d\xi, \\
\bar{\tau}_{xy} &= \frac{1}{2\pi} \int_{-\infty}^\infty e^{-|\xi|x-i\xi y} \{ ix\xi \bar{\sigma}_0 + [1 - |\xi|x] \bar{\tau}_0 \} d\xi, \\
\bar{\sigma}_z &= \frac{\nu}{\pi} \int_{-\infty}^\infty e^{-|\xi|x-i\xi y} \left[\bar{\sigma}_0 + i \frac{|\xi|}{\xi} \bar{v}_0 \right] d\xi, \\
\bar{v} &= \frac{1}{4\pi G} \int_{-\infty}^\infty e^{-|\xi|x-i\xi y} \left\{ [1 - 2\nu - |\xi|x] \frac{i}{\xi} \bar{\sigma}_0 - \left[\frac{2(1-\nu)}{|\xi|} - x \right] \bar{v}_0 \right\} d\xi, \\
\bar{u} &= -\frac{1}{4\pi G} \int_{-\infty}^\infty e^{-|\xi|x-i\xi y} \left\{ \left[\frac{2(1-\nu)}{|\xi|} + x \right] \bar{\sigma}_0 + [1 - 2\nu + |\xi|x] \frac{i}{\xi} \bar{v}_0 \right\} d\xi,
\end{aligned} \right\} \quad (11)$$

并令 $\beta_1 = c + b + x$ 和 $\beta_2 = c - b + x$, 则得

$$\left. \begin{aligned}
\bar{\sigma}_x &= -\frac{2GK}{\pi} (J_1 + 2xJ_2), \quad \bar{\sigma}_y = -\frac{2GK}{\pi} (3J_1 - 2xJ_2), \\
\bar{\tau}_{xy} &= -\frac{2GK}{\pi} (2xJ_3 - J_4), \quad \bar{\sigma}_z = -\frac{8\nu GK}{\pi} J_1, \\
\bar{v} &= -\frac{K}{\pi} [(3 - 4\nu)J_5 - 2xJ_4], \quad \bar{u} = \frac{K}{\pi} [(3 - 4\nu)J_6 + 2xJ_1],
\end{aligned} \right\} \quad (12)$$

其中

$$\left. \begin{aligned}
J_1 &= \frac{1}{2} \int_0^\infty (e^{-\beta_1 \xi} - e^{-\beta_2 \xi}) \frac{\sin[\xi(a+y)] + \sin[\xi(a-y)]}{\xi} d\xi, \\
J_2 &= \frac{1}{2} \int_0^\infty (e^{-\beta_1 \xi} - e^{-\beta_2 \xi}) \{ \sin[\xi(a+y)] + \sin[\xi(a-y)] \} d\xi, \\
J_3 &= \frac{1}{2} \int_0^\infty (e^{-\beta_1 \xi} - e^{-\beta_2 \xi}) \{ \cos[\xi(a-y)] - \cos[\xi(a+y)] \} d\xi,
\end{aligned} \right\} \quad (13)$$

$$\begin{aligned}
 J_4 &= \frac{1}{2} \int_0^\infty (e^{-\beta_1 \xi} - e^{-\beta_2 \xi}) \frac{\cos[\xi(a-y)] - \cos[\xi(a+y)]}{\xi} d\xi, \\
 J_5 &= \frac{1}{2} \int_0^\infty (e^{-\beta_1 \xi} - e^{-\beta_2 \xi}) \frac{\cos[\xi(a-y)] - \cos[\xi(a+y)]}{\xi^2} d\xi, \\
 J_6 &= \frac{1}{2} \int_0^\infty (e^{-\beta_1 \xi} - e^{-\beta_2 \xi}) \frac{\sin[\xi(a+y)] + \sin[\xi(a-y)]}{\xi^2} d\xi.
 \end{aligned}$$

利用下列诸式^[2]:

$$\begin{aligned}
 \int_0^\infty \frac{e^{-\lambda \alpha}}{\alpha} \sin(\alpha \mu) d\alpha &= \arctg \frac{\mu}{\lambda}, \quad \int_0^\infty e^{-\lambda \alpha} \sin(\alpha \mu) d\alpha = \frac{\mu}{\lambda^2 + \mu^2}, \\
 \int_0^\infty e^{-\lambda \alpha} \cos(\alpha \mu) d\alpha &= \frac{\lambda}{\lambda^2 + \mu^2}, \quad \int_0^\infty \frac{e^{-\lambda_0 \alpha} - e^{-\lambda_1 \alpha}}{\alpha} \cos(\alpha \mu) d\alpha = \frac{1}{2} \ln \frac{\lambda_1^2 + \mu^2}{\lambda_0^2 + \mu^2} \\
 &\quad (\lambda > 0, \lambda_0 > 0, \lambda_1 > 0), \\
 \int_0^\infty \frac{e^{-\alpha x} - e^{-\beta x}}{x^2} \sin(x\lambda) dx &= \frac{1}{2} \lambda \ln \frac{\lambda^2 + \beta^2}{\lambda^2 + \alpha^2} + \beta \arctg \frac{\lambda}{\beta} - \alpha \arctg \frac{\lambda}{\alpha} \\
 &\quad (\lambda > 0, \operatorname{Re} \alpha > 0, \operatorname{Re} \beta > 0),
 \end{aligned}$$

就可算出 J_1 至 J_6 的积分:

$$\begin{aligned}
 J_1 &= \frac{1}{2} \left[\arctg \frac{a+y}{c+b+x} - \arctg \frac{a+y}{c-b+x} + \right. \\
 &\quad \left. + \arctg \frac{a-y}{c+b+x} - \arctg \frac{a-y}{c-b+x} \right], \\
 J_2 &= \frac{1}{2} \left[\frac{a+y}{(a+y)^2 + (c+b+x)^2} - \frac{a+y}{(a+y)^2 + (c-b+x)^2} + \right. \\
 &\quad \left. + \frac{a-y}{(a-y)^2 + (c+b+x)^2} - \frac{a-y}{(a-y)^2 + (c-b+x)^2} \right], \\
 J_3 &= \frac{1}{2} \left[\frac{c+b+x}{(a-y)^2 + (c+b+x)^2} - \frac{c-b+x}{(a-y)^2 + (c-b+x)^2} - \right. \\
 &\quad \left. - \frac{c+b+x}{(a+y)^2 + (c+b+x)^2} + \frac{c-b+x}{(a+y)^2 + (c-b+x)^2} \right], \\
 J_4 &= \frac{1}{4} \ln \frac{[(c-b+x)^2 + (a-y)^2][(c+b+x)^2 + (a+y)^2]}{[(c+b+x)^2 + (a-y)^2][(c-b+x)^2 + (a+y)^2]}, \\
 J_6 &= \frac{1}{4} \left\{ (a+y) \ln \frac{(a+y)^2 + (c-b+x)^2}{(a+y)^2 + (c+b+x)^2} + \right. \\
 &\quad \left. + (a-y) \ln \frac{(a-y)^2 + (c-b+x)^2}{(a-y)^2 + (c+b+x)^2} \right\} + \\
 &\quad + \frac{c-b+x}{2} \left[\arctg \frac{a+y}{c-b+x} + \arctg \frac{a-y}{c-b+x} \right] - \\
 &\quad - \frac{c+b+x}{2} \left[\arctg \frac{a+y}{c+b+x} + \arctg \frac{a-y}{c+b+x} \right].
 \end{aligned} \tag{14}$$

为要求积 J_5 , 引用 $\cos[\xi|a \mp y|] = \frac{1}{2} (e^{i\xi|a \mp y|} + e^{-i\xi|a \mp y|})$ 先把 J_5 写成

$$J_5 = \frac{1}{4} (I_1 + I_2 + I_3 + I_4),$$

其中

$$I_{1,2} = \int_0^\infty [e^{-\beta_1 \xi \pm i \xi |a-y|} - e^{-\beta_2 \xi \pm i \xi |a-y|}] \frac{d\xi}{\xi^2},$$

$$I_{3,4} = - \int_0^\infty [e^{-\beta_1 \xi \pm i \xi |a+y|} - e^{-\beta_2 \xi \pm i \xi |a+y|}] \frac{d\xi}{\xi^2}.$$

设想 $I_{1,2}$ 和 $I_{3,4}$ 均有 Cauchy 主值, 依图 2 里的闭合实线并借助于 $\xi = R e^{i\theta}$ 和 $\xi = r e^{i\theta}$ 把 I_1 写成

$$\begin{aligned} & \int_r^R [e^{-\beta_1 \xi + i \xi |a-y|} - e^{-\beta_2 \xi + i \xi |a-y|}] \frac{d\xi}{\xi^2} + \\ & + \int_0^{\frac{\pi}{2}} [e^{-[\beta_1 - i |a-y|] R e^{i\theta}} - e^{-[\beta_2 - i |a-y|] R e^{i\theta}}] \frac{i d\theta}{R e^{i\theta}} + \\ & + \int_{iR}^{ir} [e^{-\beta_1 \xi + i \xi |a-y|} - e^{-\beta_2 \xi + i \xi |a-y|}] \frac{d\xi}{\xi^2} + \\ & + \int_{\frac{\pi}{2}}^0 [e^{-[\beta_1 - i |a-y|] r e^{i\theta}} - e^{-[\beta_2 - i |a-y|] r e^{i\theta}}] \frac{i d\theta}{r e^{i\theta}} = 0. \end{aligned} \quad (15)$$

使 $R \rightarrow \infty$ 和 $r \rightarrow 0$, 并因 $\cos \theta > 0$, $\sin \theta > 0$, $\beta_1 \cos \theta + |a-y| \sin \theta > 0$ 和 $\beta_2 \cos \theta + |a-y| \sin \theta > 0$, 所以自公式(15)和 I_2 的相应的式子导得

$$I_{1,3} = \mp i \int_0^\infty \{e^{-[\beta_1 - i |a-y|] i \xi} - e^{-[\beta_2 - i |a-y|] i \xi}\} \frac{d\xi}{\xi^2} \pm i(\beta_2 - \beta_1) \frac{\pi}{2}; \quad (16)$$

依同理可把 I_2 依图 2 的闭合虚线写成

$$\begin{aligned} & \int_r^R \{e^{-[\beta_1 + i |a-y|] \xi} - e^{-[\beta_2 + i |a-y|] \xi}\} \frac{d\xi}{\xi^2} + \\ & + \int_0^{-\frac{\pi}{2}} \{e^{-[\beta_1 + i |a-y|] R e^{i\theta}} - e^{-[\beta_2 + i |a-y|] R e^{i\theta}}\} \frac{i d\theta}{R e^{i\theta}} + \\ & + \int_{-iR}^{-ir} \{e^{-[\beta_1 + i |a-y|] \xi} - e^{-[\beta_2 + i |a-y|] \xi}\} \frac{d\xi}{\xi^2} + \\ & + \int_{-\frac{\pi}{2}}^0 \{e^{-[\beta_1 + i |a-y|] r e^{i\theta}} - e^{-[\beta_2 + i |a-y|] r e^{i\theta}}\} \frac{i d\theta}{r e^{i\theta}} = 0. \end{aligned} \quad (17)$$

因为 $\sin \theta < 0$, $\cos \theta > 0$, $\beta_1 \cos \theta - |a-y| \sin \theta > 0$ 和 $\beta_2 \cos \theta - |a-y| \sin \theta > 0$, 所以当 $R \rightarrow \infty$ 和 $r \rightarrow 0$ 时, 自公式(17)及 I_4 的相应的式子就可导得

$$I_{2,4} = \pm i \int_0^\infty \{e^{[\beta_1 + i |a-y|] i \xi} - e^{[\beta_2 + i |a-y|] i \xi}\} \frac{d\xi}{\xi^2} \mp i(\beta_2 - \beta_1) \frac{\pi}{2}. \quad (18)$$

把公式(16)和(18)的四个式子相加, 即得

$$\begin{aligned} J_5 &= \frac{1}{2} \int_0^\infty (e^{-|a+y|\xi} - e^{-|a-y|\xi}) \frac{\sin(\beta_1 \xi) - \sin(\beta_2 \xi)}{\xi^2} d\xi = \\ &= \frac{1}{2} \left\{ \frac{1}{2} \beta_1 \ln \frac{\beta_1^2 + |a-y|^2}{\beta_1^2 + |a+y|^2} + |a-y| \arctg \frac{\beta_1}{|a-y|} - \right. \\ &\quad \left. - |a+y| \arctg \frac{\beta_1}{|a+y|} \right\} - \frac{1}{2} \left\{ \frac{1}{2} \beta_2 \ln \frac{\beta_2^2 + |a-y|^2}{\beta_2^2 + |a+y|^2} + \right. \\ &\quad \left. + |a-y| \arctg \frac{\beta_2}{|a-y|} - |a+y| \arctg \frac{\beta_2}{|a+y|} \right\}, \end{aligned} \quad (19)$$

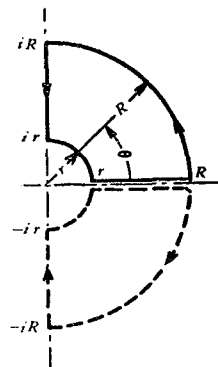


图 2 ξ 复平面内的两条积分路线

其中显示,各有关值的绝对值符号可以取消.把公式(14)和(19)代入公式(12),即得边界值问题的解答:

$$\begin{aligned}
 \bar{\sigma}_x &= -\frac{GK}{\pi} \left\{ \operatorname{arc} \operatorname{tg} \frac{a+y}{c+b+x} - \operatorname{arc} \operatorname{tg} \frac{a+y}{c-b+x} + \right. \\
 &\quad \left. + \operatorname{arc} \operatorname{tg} \frac{a-y}{c+b+x} - \operatorname{arc} \operatorname{tg} \frac{a-y}{c-b+x} \right\} - \\
 &\quad - \frac{2GKx}{\pi} \left\{ \frac{a+y}{(a+y)^2 + (c+b+x)^2} - \frac{a+y}{(a+y)^2 + (c-b+x)^2} + \right. \\
 &\quad \left. + \frac{a-y}{(a-y)^2 + (c+b+x)^2} - \frac{a-y}{(a-y)^2 + (c-b+x)^2} \right\}, \\
 \bar{\sigma}_y &= -\frac{3GK}{\pi} \left\{ \operatorname{arc} \operatorname{tg} \frac{a+y}{c+b+x} - \operatorname{arc} \operatorname{tg} \frac{a+y}{c-b+x} + \right. \\
 &\quad \left. + \operatorname{arc} \operatorname{tg} \frac{a-y}{c+b+x} - \operatorname{arc} \operatorname{tg} \frac{a-y}{c-b+x} \right\} + \\
 &\quad + \frac{2GKx}{\pi} \left\{ \frac{a+y}{(a+y)^2 + (c+b+x)^2} - \frac{a+y}{(a+y)^2 + (c-b+x)^2} + \right. \\
 &\quad \left. + \frac{a-y}{(a-y)^2 + (c+b+x)^2} - \frac{a-y}{(a-y)^2 + (c-b+x)^2} \right\}, \\
 \bar{\tau}_{xy} &= -\frac{2GKx}{\pi} \left\{ \frac{c+b+x}{(a+y)^2 + (c+b+x)^2} - \frac{c-b+x}{(a-y)^2 + (c-b+x)^2} - \right. \\
 &\quad \left. - \frac{c+b+x}{(a+y)^2 + (c+b+x)^2} + \frac{c-b+x}{(a+y)^2 + (c-b+x)^2} \right\} + \\
 &\quad + \frac{GK}{2\pi} \ln \frac{[(c-b+x)^2 + (a-y)^2][(c+b+x)^2 + (a+y)^2]}{[(c+b+x)^2 + (a-y)^2][(c-b+x)^2 + (a+y)^2]}, \\
 \bar{\sigma}_z &= -\frac{4\nu GK}{\pi} \left\{ \operatorname{arc} \operatorname{tg} \frac{a+y}{c+b+x} - \operatorname{arc} \operatorname{tg} \frac{a+y}{c-b+x} + \right. \\
 &\quad \left. + \operatorname{arc} \operatorname{tg} \frac{a-y}{c+b+x} - \operatorname{arc} \operatorname{tg} \frac{a-y}{c-b+x} \right\}, \\
 \bar{v} &= -\frac{(3-4\nu)K}{4\pi} \left\{ (c+b+x) \ln \frac{(c+b+x)^2 + (a-y)^2}{(c+b+x)^2 + (a+y)^2} - \right. \\
 &\quad - (c-b+x) \ln \frac{(c-b+x)^2 + (a-y)^2}{(c-b+x)^2 + (a+y)^2} + \\
 &\quad + 2(a-y) \left[\operatorname{arc} \operatorname{tg} \frac{c+b+x}{a-y} - \operatorname{arc} \operatorname{tg} \frac{c-b+x}{a-y} \right] - \\
 &\quad - 2(a+y) \left[\operatorname{arc} \operatorname{tg} \frac{c+b+x}{a+y} - \operatorname{arc} \operatorname{tg} \frac{c-b+x}{a+y} \right] \left. \right\} + \\
 &\quad + \frac{Kx}{2\pi} \ln \frac{[(c-b+x)^2 + (a-y)^2][(c+b+x)^2 + (a+y)^2]}{[(c+b+x)^2 + (a-y)^2][(c-b+x)^2 + (a+y)^2]}, \\
 \bar{u} &= \frac{(3-4\nu)K}{4\pi} \left\{ (a+y) \ln \frac{(a+y)^2 + (c-b+x)^2}{(a+y)^2 + (c+b+x)^2} + \right.
 \end{aligned} \tag{20}$$

$$\begin{aligned}
& + (a-y) \ln \frac{(a-y)^2 + (c-b+x)^2}{(a-y)^2 + (c+b+x)^2} + \\
& + 2(c-b+x) \left[\operatorname{arc} \operatorname{tg} \frac{a+y}{c-b+x} + \operatorname{arc} \operatorname{tg} \frac{a-y}{c-b+x} \right] - \\
& - 2(c+b+x) \left[\operatorname{arc} \operatorname{tg} \frac{a+y}{c+b+x} + \operatorname{arc} \operatorname{tg} \frac{a-y}{c+b+x} \right] \Big\} + \\
& + \frac{Kx}{\pi} \left[\operatorname{arc} \operatorname{tg} \frac{a+y}{c+b+x} - \operatorname{arc} \operatorname{tg} \frac{a+y}{c-b+x} + \right. \\
& \left. + \operatorname{arc} \operatorname{tg} \frac{a-y}{c+b+x} - \operatorname{arc} \operatorname{tg} \frac{a-y}{c-b+x} \right].
\end{aligned}$$

三、半无限弹性组合体里的热应力和位移

把公式(3)至(8)跟公式(20)相加, 并引进关系 $x = c\bar{x}$, $y = c\bar{y}$, $a = c\bar{a}$ 和 $b = c\bar{b}$, 就得到本题的全部解:

$$\begin{aligned}
\sigma_x = & -\frac{GK}{\pi} \left\{ \operatorname{arc} \operatorname{tg} \frac{\bar{x}-1-\bar{b}}{\bar{y}-\bar{a}} - \operatorname{arc} \operatorname{tg} \frac{\bar{x}-1+\bar{b}}{\bar{y}-\bar{a}} - \operatorname{arc} \operatorname{tg} \frac{\bar{x}-1-\bar{b}}{\bar{y}+\bar{a}} + \right. \\
& + \operatorname{arc} \operatorname{tg} \frac{\bar{x}-1+\bar{b}}{\bar{y}+\bar{a}} + \operatorname{arc} \operatorname{tg} \frac{\bar{a}+\bar{y}}{1+\bar{b}+\bar{x}} - \operatorname{arc} \operatorname{tg} \frac{\bar{a}+\bar{y}}{1-\bar{b}+\bar{x}} + \\
& + \operatorname{arc} \operatorname{tg} \frac{\bar{a}-\bar{y}}{1+\bar{b}+\bar{x}} - \operatorname{arc} \operatorname{tg} \frac{\bar{a}-\bar{y}}{1-\bar{b}+\bar{x}} + 2\bar{x} \left[(\bar{a}+\bar{y}) \left(\frac{1}{\bar{r}_7^2} - \frac{1}{\bar{r}_6^2} \right) + \right. \\
& \left. \left. + (\bar{a}-\bar{y}) \left(\frac{1}{\bar{r}_8^2} - \frac{1}{\bar{r}_5^2} \right) \right] \right\}, \\
\sigma_y = & -\frac{GK}{\pi} \left\{ \operatorname{arc} \operatorname{tg} \frac{\bar{y}-\bar{a}}{\bar{x}-1-\bar{b}} - \operatorname{arc} \operatorname{tg} \frac{\bar{y}+\bar{a}}{\bar{x}-1-\bar{b}} - \operatorname{arc} \operatorname{tg} \frac{\bar{y}-\bar{a}}{\bar{x}-1+\bar{b}} + \right. \\
& + \operatorname{arc} \operatorname{tg} \frac{\bar{y}+\bar{a}}{\bar{x}-1+\bar{b}} + 3 \left[\operatorname{arc} \operatorname{tg} \frac{\bar{a}+\bar{y}}{1+\bar{b}+\bar{x}} - \operatorname{arc} \operatorname{tg} \frac{\bar{a}+\bar{y}}{1-\bar{b}+\bar{x}} + \right. \\
& + \operatorname{arc} \operatorname{tg} \frac{\bar{a}-\bar{y}}{1+\bar{b}+\bar{x}} - \operatorname{arc} \operatorname{tg} \frac{\bar{a}-\bar{y}}{1-\bar{b}+\bar{x}} \Big] - 2\bar{x} \left[(\bar{a}+\bar{y}) \left(\frac{1}{\bar{r}_7^2} - \frac{1}{\bar{r}_6^2} \right) + \right. \\
& \left. \left. + (\bar{a}-\bar{y}) \left(\frac{1}{\bar{r}_8^2} - \frac{1}{\bar{r}_5^2} \right) \right] \right\}, \\
\tau_{xy} = & \frac{GK}{\pi} \left\{ \ln \frac{\bar{r}_1 \bar{r}_3 \bar{r}_5 \bar{r}_7}{\bar{r}_2 \bar{r}_4 \bar{r}_6 \bar{r}_8} - 2\bar{x} \left[(1+\bar{b}+\bar{x}) \left(\frac{1}{\bar{r}_8^2} - \frac{1}{\bar{r}_7^2} \right) + (1-\bar{b}+\bar{x}) \left(\frac{1}{\bar{r}_6^2} - \frac{1}{\bar{r}_5^2} \right) \right] \right\}, \\
\sigma_{xi} = & -2GK - \frac{4\nu GK}{\pi} \left\{ \operatorname{arc} \operatorname{tg} \frac{\bar{a}+\bar{y}}{1+\bar{b}+\bar{x}} - \operatorname{arc} \operatorname{tg} \frac{\bar{a}+\bar{y}}{1-\bar{b}+\bar{x}} + \right. \\
& \left. + \operatorname{arc} \operatorname{tg} \frac{\bar{a}-\bar{y}}{1+\bar{b}+\bar{x}} - \operatorname{arc} \operatorname{tg} \frac{\bar{a}-\bar{y}}{1-\bar{b}+\bar{x}} \right\}, \\
\sigma_{xa} = & -\frac{4\nu GK}{\pi} \left\{ \operatorname{arc} \operatorname{tg} \frac{\bar{a}+\bar{y}}{1+\bar{b}+\bar{x}} - \operatorname{arc} \operatorname{tg} \frac{\bar{a}+\bar{y}}{1-\bar{b}+\bar{x}} + \right. \\
& \left. + \operatorname{arc} \operatorname{tg} \frac{\bar{a}-\bar{y}}{1+\bar{b}+\bar{x}} - \operatorname{arc} \operatorname{tg} \frac{\bar{a}-\bar{y}}{1-\bar{b}+\bar{x}} \right\},
\end{aligned}$$

$$\begin{aligned}
 v = & \frac{Kc}{2\pi} \left\{ (\bar{x} - 1 - \bar{b}) \ln \frac{\bar{r}_1}{\bar{r}_2} + (\bar{x} - 1 + \bar{b}) \ln \frac{\bar{r}_3}{\bar{r}_4} + \right. \\
 & + (\bar{y} - \bar{a}) \left[\arctg \frac{\bar{x} - 1 - \bar{b}}{\bar{y} - \bar{a}} - \arctg \frac{\bar{x} - 1 + \bar{b}}{\bar{y} - \bar{a}} \right] - \\
 & - (\bar{y} + \bar{a}) \left[\arctg \frac{\bar{x} - 1 - \bar{b}}{\bar{y} + \bar{a}} - \arctg \frac{\bar{x} - 1 + \bar{b}}{\bar{y} + \bar{a}} \right] \left. \right\} - \\
 & - \frac{(3 - 4\nu)Kc}{2\pi} \left\{ (1 + \bar{b} + \bar{x}) \ln \frac{\bar{r}_8}{\bar{r}_7} + (1 - \bar{b} + \bar{x}) \ln \frac{\bar{r}_6}{\bar{r}_5} + \right. \\
 & + (\bar{a} - \bar{y}) \left[\arctg \frac{1 + \bar{b} + \bar{x}}{\bar{a} - \bar{y}} - \arctg \frac{1 - \bar{b} + \bar{x}}{\bar{a} - \bar{y}} \right] - \\
 & - (\bar{a} + \bar{y}) \left[\arctg \frac{1 + \bar{b} + \bar{x}}{\bar{a} + \bar{y}} - \arctg \frac{1 - \bar{b} + \bar{x}}{\bar{a} + \bar{y}} \right] \left. \right\} - \frac{Kc\bar{x}}{\pi} \ln \frac{\bar{r}_6\bar{r}_8}{\bar{r}_5\bar{r}_7}, \\
 u = & \frac{Kc}{2\pi} \left\{ (\bar{y} - \bar{a}) \ln \frac{\bar{r}_1}{\bar{r}_4} - (\bar{y} + \bar{a}) \ln \frac{\bar{r}_2}{\bar{r}_3} + \right. \\
 & + (\bar{x} - 1 - \bar{b}) \left[\arctg \frac{\bar{y} - \bar{a}}{\bar{x} - 1 - \bar{b}} - \arctg \frac{\bar{y} + \bar{a}}{\bar{x} - 1 - \bar{b}} \right] - \\
 & - (\bar{x} - 1 + \bar{b}) \left[\arctg \frac{\bar{y} - \bar{a}}{\bar{x} - 1 + \bar{b}} - \arctg \frac{\bar{y} + \bar{a}}{\bar{x} - 1 + \bar{b}} \right] \left. \right\} + \\
 & + \frac{(3 - 4\nu)Kc}{2\pi} \left\{ (\bar{a} + \bar{y}) \ln \frac{\bar{r}_6}{\bar{r}_7} + (\bar{a} - \bar{y}) \ln \frac{\bar{r}_5}{\bar{r}_8} + \right. \\
 & + (1 - \bar{b} + \bar{x}) \left[\arctg \frac{\bar{a} + \bar{y}}{1 - \bar{b} + \bar{x}} + \arctg \frac{\bar{a} - \bar{y}}{1 - \bar{b} + \bar{x}} \right] - \\
 & - (1 + \bar{b} + \bar{x}) \left[\arctg \frac{\bar{a} + \bar{y}}{1 + \bar{b} + \bar{x}} + \arctg \frac{\bar{a} - \bar{y}}{1 + \bar{b} + \bar{x}} \right] \left. \right\} + \\
 & + \frac{Kc}{\pi} \bar{x} \left[\arctg \frac{\bar{a} + \bar{y}}{1 + \bar{b} + \bar{x}} - \arctg \frac{\bar{a} + \bar{y}}{1 - \bar{b} + \bar{x}} + \right. \\
 & + \arctg \frac{\bar{a} - \bar{y}}{1 + \bar{b} + \bar{x}} - \arctg \frac{\bar{a} - \bar{y}}{1 - \bar{b} + \bar{x}} \left. \right],
 \end{aligned} \tag{21}$$

其中 σ_{zi} 和 σ_{za} 各代表矩形内外沿 z 轴的应力,并曾用了符号

$$\begin{aligned}
 \bar{r}_1^2 &= (\bar{x} - 1 - \bar{b})^2 + (\bar{y} - \bar{a})^2, & \bar{r}_2^2 &= (\bar{x} - 1 - \bar{b})^2 + (\bar{y} + \bar{a})^2, \\
 \bar{r}_3^2 &= (\bar{x} - 1 + \bar{b})^2 + (\bar{y} + \bar{a})^2, & \bar{r}_4^2 &= (\bar{x} - 1 + \bar{b})^2 + (\bar{y} - \bar{a})^2, \\
 \bar{r}_5^2 &= (1 - \bar{b} + \bar{x})^2 + (\bar{a} - \bar{y})^2, & \bar{r}_6^2 &= (1 - \bar{b} + \bar{x})^2 + (\bar{a} + \bar{y})^2, \\
 \bar{r}_7^2 &= (1 + \bar{b} + \bar{x})^2 + (\bar{a} + \bar{y})^2, & \bar{r}_8^2 &= (1 + \bar{b} + \bar{x})^2 + (\bar{a} - \bar{y})^2.
 \end{aligned}$$

四、例题与讨论

选用两种铁镍合金,其主要性态是: $E = E_i = E_a = 2 \times 10^6 \text{ kg/cm}^2$, $\alpha_i = 5 \times 10^{-6} 1/^\circ\text{C}$, $\alpha_a = 2 \times 10^{-6} 1/^\circ\text{C}$, $\nu = \nu_i = \nu_a = 0.3$, $\eta_0 = \alpha_i - \alpha_a = 3 \times 10^{-6} 1/^\circ\text{C}$, $G = E/2(1 + \nu) = 7.7 \times 10^5 \text{ kg/cm}^2$; 取 $GK = 1000 \text{ kg}$, 则 $T_0 = 233^\circ\text{C}$, $K = \frac{1 + \nu}{1 - \nu} \eta_0 T_0 = 1.298 \times 10^{-3}$.

又设 $c = 10 \text{ cm}$, $\bar{a} = 0.5$, $\bar{b} = 0.25$. 为了照顾到各物理量的连续性和非连续性明显出

现, 取 $\bar{y} = 0, 0.25, 0.4, 0.5, 0.6, 0.75, 1, 1.5$ 和 $\bar{x} = 0, 0.5, 0.75, 1, 1.25, 1.5$.

数字计算按照图 3 的各点进行, 用横竖线标志其所属的坐标距离, 把数字计算得出的结果绘成图 4 至图 9, 其中实线表示矩形以外的物理量, 虚线表示矩形里边的物理量.

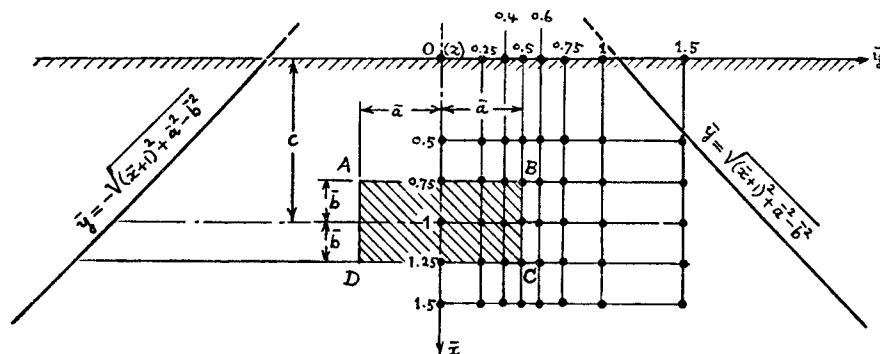


图 3 数字计算点分布图; $\sigma_{za} = 0$ 的双曲线曲面的轨迹

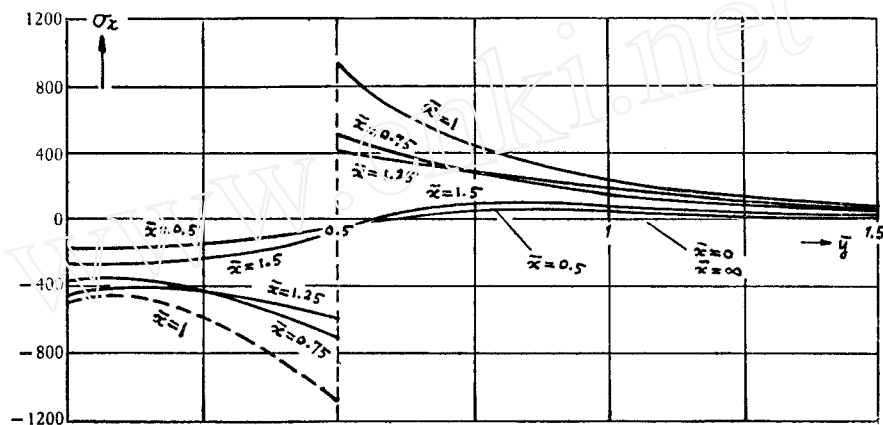


图 4 应力 σ_x 的变化

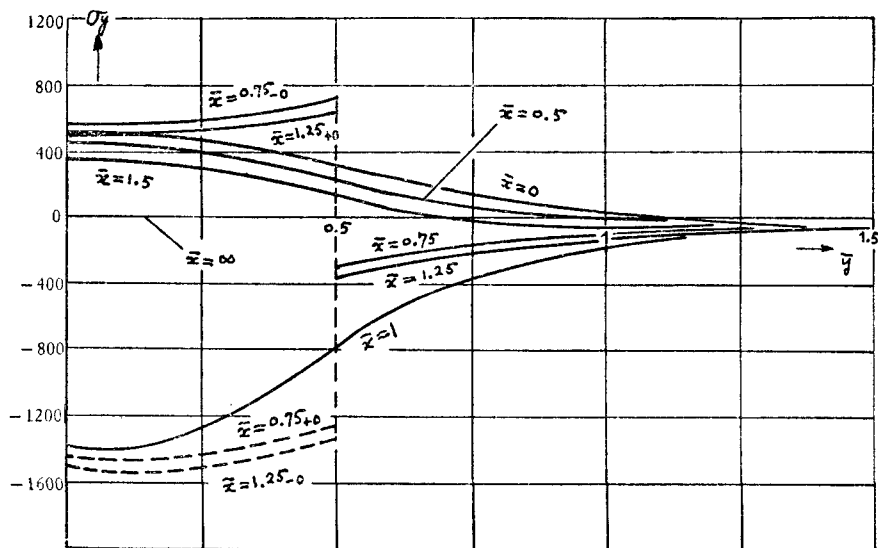
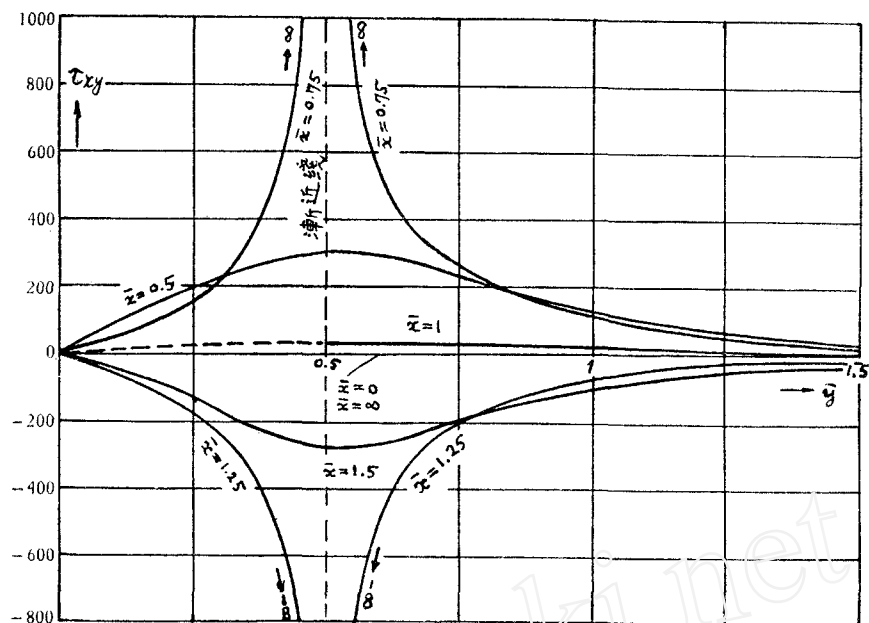
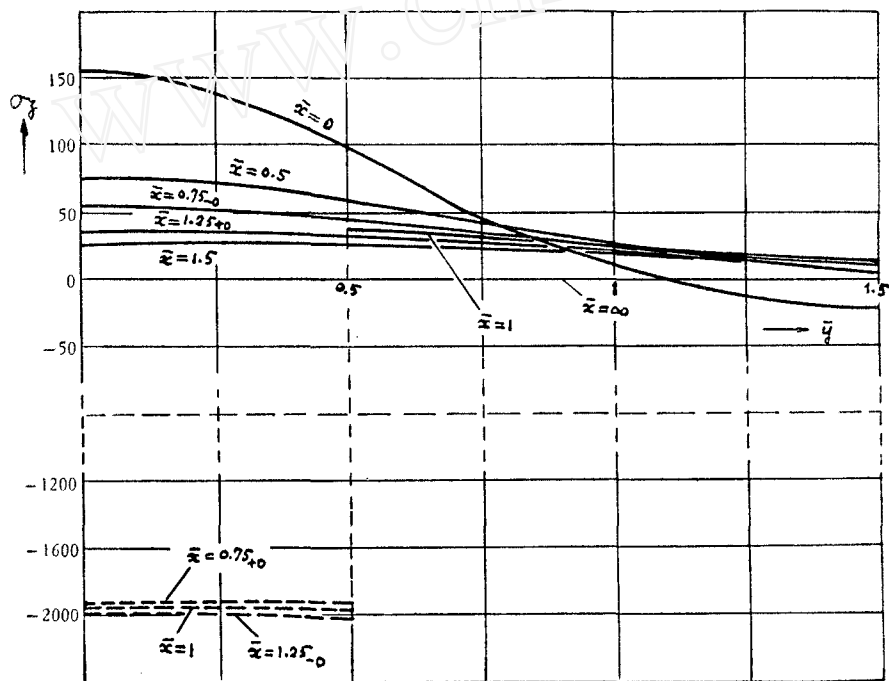
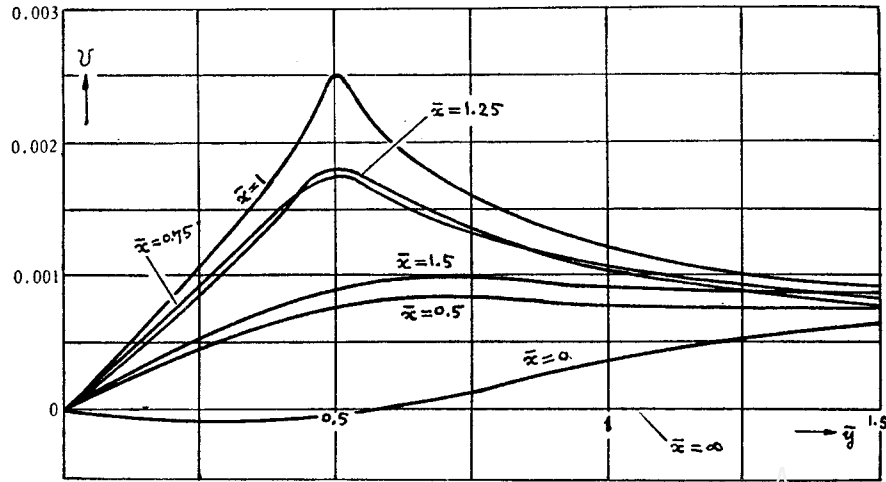
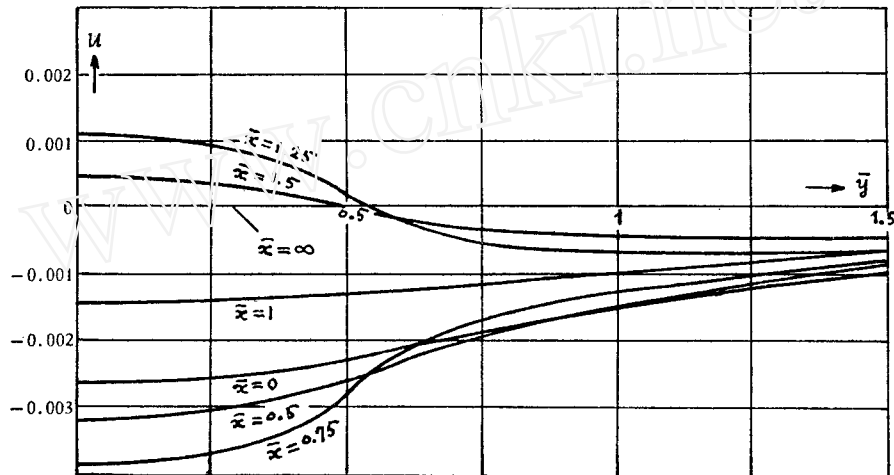


图 5 应力 σ_y 的变化

图6 应力 τ_{xy} 的变化图7 应力 σ_{xi} 和 σ_{za} 的变化

为清晰计,在图7里采用两种不同的标尺。

首先,图4至图9显示:当 σ_x 和 σ_y 垂直于分界线时,它们是连续的;当它们平行于分界线时,它们是非连续的; σ_x 在分界线上都是非连续的,因为 σ_x 总是平行于分界面;在矩形的角上, τ_{xy} 变为无限大;在分界线上, v 和 u 都连续的。图中曲线所显示的连续性

图8 位移 v 的变化图9 位移 u 的变化

和非连续性情况均与有关的原理符合^[3].

其次,尚须用分析来肯定一些为曲线所不易规定的细微性态,可以验证: $\left(\frac{\partial}{\partial \bar{y}} \sigma_x\right)_{\bar{y}=0, \bar{x}=0} = \left(\frac{\partial}{\partial \bar{y}} \sigma_y\right)_{\bar{y}=0, \bar{x}=0} = \left(\frac{\partial}{\partial \bar{y}} \tau_{xy}\right)_{\bar{y}=0, \bar{x}=0} = 0$, $\left(\frac{\partial}{\partial \bar{y}} \tau_{xy}\right)_{\bar{y}=0, \bar{x}=0} \equiv 0$, $\left(\frac{\partial}{\partial \bar{y}} \sigma_{zi}\right)_{\bar{y}=0} = \left(\frac{\partial}{\partial \bar{y}} \sigma_{xa}\right)_{\bar{y}=0} = 0$, $\left(\frac{\partial v}{\partial \bar{y}}\right)_{\bar{y}=0} \equiv 0$, $\left(\frac{\partial u}{\partial \bar{y}}\right)_{\bar{y}=0} = 0$; 由于

$$\begin{aligned} \left(\frac{\partial}{\partial \bar{y}} \sigma_x\right)_{\bar{y}=0, \bar{x} \neq 0} &= -\left(\frac{\partial}{\partial \bar{y}} \sigma_y\right)_{\bar{y}=0, \bar{x} \neq 0} = -\frac{4GK\bar{x}}{\pi} \left(\frac{1 + \bar{b} + \bar{x}}{\bar{a}^2 + (1 + \bar{b} + \bar{x})^2} + \right. \\ &\quad \left. + \frac{1 - \bar{b} + \bar{x}}{\bar{a}^2 + (1 - \bar{b} + \bar{x})^2} \right) \frac{f(\bar{a}, \bar{b}, \bar{x})}{[\bar{a}^2 + (1 + \bar{b} + \bar{x})^2][\bar{a}^2 + (1 - \bar{b} + \bar{x})^2]}, \end{aligned}$$

其中

$$\begin{aligned} f(\bar{a}, \bar{b}, \bar{x}) &= (1 + \bar{b} + \bar{x})[\bar{a}^2 + (1 - \bar{b} + \bar{x})^2] - \\ &\quad - (1 - \bar{b} + \bar{x})[\bar{a}^2 + (1 + \bar{b} + \bar{x})^2] = 2\bar{b}[\bar{a}^2 + \bar{b}^2 - (1 + \bar{x})^2], \end{aligned}$$

所以

$$\left(\frac{\partial \sigma_x}{\partial \bar{y}}\right)_{\substack{\bar{y}=0 \\ \bar{x}>0}} = -\left(\frac{\partial \sigma_y}{\partial \bar{y}}\right)_{\substack{\bar{y}=0 \\ \bar{x}>0}} \equiv 0, \text{ 当 } \bar{a}^2 + \bar{b}^2 \leq (1 + \bar{x})^2 \text{ 时.}$$

再次, 条件 $\sigma_{za} = 0$ 能给出双曲线 $\bar{y} = \pm \sqrt{(\bar{x} + 1)^2 + \bar{a}^2 - \bar{b}^2}$; 已把这两条曲线绘于图 3; 在点 $(-1, \pm \sqrt{\bar{a}^2 - \bar{b}^2})$ 处, 双曲线与直线 $\bar{y} = \pm \sqrt{\bar{a}^2 - \bar{b}^2}$ 相切; 双曲线的渐近线是 $\bar{y} = \pm(\bar{x} + 1)$.

五、应力和位移在分界线上的连续性

关于 σ_z 在分界线上的连续性, 可见公式 (6). 由于 τ_{xy} , v 和 u 的各项系显明的连续函数, 所以不用检查.

根据原理, 纯弹性力学边界值问题所给出的解都连续地跨越分界线, 所以此地只需要对 $\bar{\sigma}_x$ 和 $\bar{\sigma}_y$ 进行检查.

因为在 AB 和 CD 分界线上有

$$(\bar{\sigma}_x)_{x=c-b \mp \delta} = -\frac{GK}{\pi} \left[\arctg \frac{-2b \mp \delta}{y-a} - \arctg \frac{\mp \delta}{y-a} - \arctg \frac{-2b \mp \delta}{y+a} + \arctg \frac{\mp \delta}{y+a} \right]$$

和

$$(\bar{\sigma}_x)_{x=c+b \mp \delta} = -\frac{GK}{\pi} \left[\arctg \frac{\mp \delta}{y-a} - \arctg \frac{2b \mp \delta}{y-a} - \arctg \frac{\mp \delta}{y+a} + \arctg \frac{2b \mp \delta}{y+a} \right],$$

所以导出

$$(\sigma_x)_{x=c \mp b \pm 0} - (\sigma_x)_{x=c \mp b \mp 0} = 0; \quad (22)$$

更因在 BC 和 AD 两段分界线上有

$$(\bar{\sigma}_x)_{y=a \mp \delta} = -\frac{GK}{\pi} \left[\arctg \frac{x-c-b}{\mp \delta} - \arctg \frac{x-c+b}{\mp \delta} - \arctg \frac{x-c-b}{2a \mp \delta} + \arctg \frac{x-c+b}{2a \mp \delta} \right]$$

和

$$(\bar{\sigma}_x)_{y=-a \mp \delta} = -\frac{GK}{\pi} \left[\arctg \frac{x-c-b}{-2a \mp \delta} - \arctg \frac{x-c+b}{-2a \mp \delta} - \arctg \frac{x-c-b}{\mp \delta} + \arctg \frac{x-c+b}{\mp \delta} \right],$$

所以求得

$$(\sigma_x)_{y=\pm a \mp 0} - (\sigma_x)_{y=\pm a \pm 0} = -\frac{E\eta_0 T_0}{1-\nu}; \quad (23)$$

又因在 AB 和 CD 分界线上有

$$(\bar{\sigma}_y)_{x=c-b \mp \delta} = -\frac{GK}{\pi} \left[\arctg \frac{y-a}{-2b \mp \delta} - \arctg \frac{y+a}{-2b \mp \delta} - \arctg \frac{y-a}{\mp \delta} + \arctg \frac{y+a}{\mp \delta} \right]$$

和

$$(\bar{\sigma}_y)_{x=c+b \mp \delta} = -\frac{GK}{\pi} \left[\arctg \frac{y-a}{\mp \delta} - \arctg \frac{y+a}{\mp \delta} - \arctg \frac{y-a}{2b \mp \delta} + \arctg \frac{y+a}{2b \mp \delta} \right],$$

所以得出

$$(\sigma_y)_{x=c \mp b \pm 0} - (\sigma_y)_{x=c \mp b \mp 0} = -\frac{E\eta_0 T_0}{1-\nu}; \quad (24)$$

复因在 BC 和 AD 分界线上有

$$(\bar{\sigma}_y)_{y=a\mp\delta} = -\frac{GK}{\pi} \left[\operatorname{arc\,tg} \frac{\mp\delta}{x-c-b} - \operatorname{arc\,tg} \frac{2a\mp\delta}{x-c-b} - \right. \\ \left. - \operatorname{arc\,tg} \frac{\mp\delta}{x-c+b} + \operatorname{arc\,tg} \frac{2a\mp\delta}{x-c+b} \right]$$

和

$$(\bar{\sigma}_y)_{y=-a\mp\delta} = -\frac{GK}{\pi} \left[\operatorname{arc\,tg} \frac{-2a\mp\delta}{x-c-b} - \operatorname{arc\,tg} \frac{\mp\delta}{x-c-b} - \right. \\ \left. - \operatorname{arc\,tg} \frac{-2a\mp\delta}{x-c+b} + \operatorname{arc\,tg} \frac{\mp\delta}{x-c+b} \right],$$

所以得到

$$(\sigma_y)_{y=\pm a\mp 0} - (\sigma_y)_{y=\pm a\pm 0} = 0. \quad (25)$$

公式(22)至(25)表示的连续性或突跃性都与有关的原理符合^[3].

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WÄRMESpannungen UND VERSchieBungen IM HALBRAUM MIT RECHTECKIGEM EINSchluss

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